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NOTES ON SEQUENTIAL OLIGOPOLY

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A Sequential Move Oligopoly Game

Two firms, labelled $i = 1, 2$, play a sequential move Cournot (quantity-setting) game. In each period t , $t = 0, 1, \dots$, firm 1 moves first and picks an output level q_{1t} . Then having seen q_{1t} , firm 2 moves and picks an output level q_{2t} . We call q_{it} the action of firm i at time t . We assume q_{it} is a member of the action space A_i for all t . The period t payoff to firm i when actions q_{1t} and q_{2t} are taken is

$$(1.1) \quad \pi_{it}(q_{1t}, q_{2t}) = p(q_{1t} + q_{2t})q_{it}$$

where $p(\cdot)$ is the industry demand function. We assume $p(q)$ is differentiable, monotonically decreasing in q on a finite interval $[0, m]$ and that $p(q) \rightarrow 0$ as q increases to m and $p(q)$ equals zero for all $q \geq m$.

A strategy σ_i for firm i is a sequence of functions $\sigma_{i1}, \sigma_{i2}, \dots$, one for each period t . The function for period t determines player i 's actions as a function of the actions taken by both players times before time t . Let the history faced by player 1 at time t be denoted h_{1t} where

$$h_{1t} = (q_{11}, q_{21}, \dots, q_{1t-1}, q_{2t-1}).$$

That is, h_{1t} records the output levels of both players in all periods before t . Let $H_{1t} = \{h_{1t} | q_{is} \in A_i \text{ for all } 1 \leq s < t\}$. In period t player 2 moves after having observed the current output q_{1t} produced by player 1. Thus the history facing player 2 at time t is $h_{2t} = (h_{1t}; q_{1t})$. Let

$$H_{2t} = \{h_{2t} | q_{is} \in A_1 \text{ for } 1 \leq s \leq t \text{ and } q_{2s} \in A_2 \text{ for } 1 \leq s < t\}.$$

A strategy σ_i for player i is a sequence of functions $\{\sigma_{it}\}_{t=1}^{\infty}$ where $\sigma_{it}: H_{it} \rightarrow A_i$. Let the strategy space of player i be

$$S_i = \{\sigma_i = (\sigma_{it})_{t=1}^{\infty} | \sigma_{it}: H_{it} \rightarrow A_i\}.$$

Let $\sigma = (\sigma_1, \sigma_2)$ and $S = S_1 \times S_2$. We need to define payoffs over strategies. We first define payoffs over outcomes. An outcome path q^0 is a collection of actions for both players, one each t . That is $q^0 = \{q_{1t}, q_{2t}\}_{t=1}^{\infty}$. The payoff to firm i under outcome path q^0 is

$$(1.2) \quad V_i(q^0) = \sum_{t=1}^{\infty} \delta^t \pi_i(q_{1t}, q_{2t}).$$

Likewise, the payoff to firm i from t onwards under the outcome path q^t from t onwards is

$$(1.3) \quad V_{it}(q^t) = \sum_{s=t}^{\infty} \delta^{s-t} \pi_i(q_{1s}, q_{2s})$$

where $q^t = (q_{1t}, q_{2t}, q_{1t+1}, q_{2t+1}, \dots)$.

Given any history h_{1t} a strategy vector $\sigma_1(\cdot | h_{1t})$, $\sigma_2(\cdot | h_{2t})$ generates an outcome path from t onward, which is inductively defined as,

$$(1.4) \quad q_{1t} = \sigma_1(h_{1t} | h_{1t})$$

$$q_{2t} = \sigma_2(h_{2t} | h_{1t}) \text{ where } h_{2t} = (h_{1t}; q_{1t})$$

$$q_{1t+1} = \sigma_1(h_{1t+1} | h_{1t}) \text{ where } h_{1t+1} = (h_{1t}; q_{1t}, q_{2t})$$

$$q_{2t+1} = \sigma_2(h_{2t+1} | h_{1t}) \text{ where } h_{2t+1} = (h_{1t}; q_{1t}, q_{2t}, q_{1t+1}), \text{ and soon.}$$

Payoffs over strategies $\sigma_1(\cdot | h_{1t})$, $\sigma_2(\cdot | h_{2t})$ are given by

$$V_{it}(\sigma_1(\cdot | h_{1t}), \sigma_2(\cdot | h_{2t})) = \sum_{s=t}^{\infty} \int \delta^{s-t} \pi_i(q_{1s}, q_{2s})$$

where $q^t = (q_{1t}, q_{2t}, q_{1t+1}, q_{2t+1}, \dots)$ is defined by (1.4).

Let $S_i(h_{1t})$ denote the set of strategies for player i from t onward, given history h_{1t} . That is

$$(1.6) \quad S_i(h_{1t}) = \{ \sigma_i(\cdot | h_{1t}) = (\sigma_{is}(\cdot | h_{1t}))_{s=t}^{\infty} \mid \sigma_{is}(\cdot | h_{1t}) : H_{1t}^S \rightarrow A_1 \}$$

where $H_{1t}^S = \{h_{1t}^S = (q_{1t}, q_{2t}, \dots, q_{1s-1}, q_{2s-1}) \mid q_{ir} \in A_i \text{ all } t \leq r < s\}$. Let $S_2(h_{2t})$ be defined in an analogous fashion. We then have

Definition. $\sigma = (\sigma_1, \sigma_2) \in S$ is a subgame perfect Nash equilibrium if for each $t = 1, 2, \dots$. The following conditions hold: for each $h_{1t} \in H_{1t}$.

$$(1.7) \quad v_{1t}(\sigma_1(\cdot | h_{1t}), \sigma_2(\cdot | h_{2t})) \geq v_{1t}(\sigma'_1(\cdot | h_{1t}), \sigma_2(\cdot | h'_{2t}))$$

for all $\sigma'_1(\cdot | h_{1t}) \in S_1(h_{1t})$ where $h'_{2t} = (h_{1t}, \sigma'_1(h_{1t} | h_{1t}))$ and for each $h_{2t} \in H_{2t}$

$$(1.8) \quad v_{2t}(\sigma_1(\cdot | h_{1t}), \sigma_2(\cdot | h_{2t})) \geq v_{2t}(\sigma_1(\cdot | h_{1t}), \sigma'_2(\cdot | h_{2t}))$$

for all $\sigma'_2(\cdot | h_{2t}) \in S_2(h_{2t})$.

Notice that in each period t player 1 is a "Stackelberg leader" in the sense that player 1 when considering a deviation to some $\sigma'_1(\cdot | h_{1t})$ takes account of the fact that the action he adopts at t , say $\sigma'_1(h_{1t} | h_{1t})$, will affect the action taken by player 2 by affecting the history that player 2 confronts when it is his turn to move.